

Advanced Data Structures

Lecture 04: Predecessor and Range Minimum Query Data Structures

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https://pingo.scc.kit.edu/267787

Recap



Succinct Planar Graphs

- using spanning tree of graph and
- special spanning tree of dual graph
- both represented succinctly
- represent planar graph succinctly
- store whether edge is in spanning tree or not

Predecessor and Successor



Setting

- assume universe $\mathcal{U} = [0, u)$
- \blacksquare let $u=2^w$
- sorted array of *n* integers $A \subseteq \mathcal{U}$
- $\log n \le w$ since $n \le u$

Definition: Predecessor & Successor

Given an array A of n integers from an universe \mathcal{U} and an integer $x \in \mathcal{U}$, the predecessor and successor of x in A are

- $pred(A, x) = \max\{y \in A : y \le x\}$
- $succ(A, x) = min\{y \in A: y \ge x\}$

•	•	_		•	5		•	_	•
0	1	2	4	7	10	20	21	22	32

- pred(3) = 2
- *pred*(10) = 10
- succ(23) = 32
- in what time and space can we solve this using bit vectors? PINGO

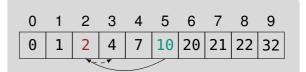
Predecessor and Successor: Simple Solutions



- binary search
- $O(\log n)$ query time
- no space overhead
- using bit vector
- O(1) query time
- = u + o(u) bits space

Predecessor of x in Bit Vector

- $z = rank_1(x + 2)$
- predecessor is select₁(z)



111010010010000000001110000000001

- $rank_1(21) = 6$
- *select*₁(6) = 10
- pred(19) = 10

Elias-Fano Coding [Eli74; Fan71] (1/3)



- *n* integers from universe $\mathcal{U} = [0, u)$
- split number in upper and lower halves
- upper half: [log n] most significant bits
- lower half: $\lceil \log u \log n \rceil$ remaining bits

Upper Half

- monotonous sequence of [log n] bit integers
- not strictly monotonous
- \blacksquare let p_0, \ldots, p_{n-1} be sequence
- use bit vector of length 2n + 1 bits
- \blacksquare represent p_i with a 1 at position $i + p_i$
- \blacksquare rank and select support requires o(n) bits

Lower Half

- store lower half plain using $\lceil \log \frac{u}{n} \rceil$ bits
- $n \log \left[\frac{u}{n} \right]$ bits for lower half

•	•	_		•	5	•	•	_	
0	1	2	4	7	10	20	21	22	32

0: 000000

10: 001010

1: 000001

20: 010100

2: 000010

21: 010101

4: 000100

22: 010110

7: 000111

30: 100000

Elias-Fano Coding (2/3)



Access i-th Element

- upper: $select_1(i) i$
- lower: corresponding bits from lower bit vector

Predecessor x

- let x' be $\lceil \log n \rceil$ MSB of x
- $p = select_0(x') select_0(0) returns 0$
- scan corresponding values in lower till predecessor is found
- how many elements do we have to scan?
 PINGO
- scanning O(u/n) elements

0	1	2	3	4	5	6	7	8	9			
0	1	2	4	7	10	20	21	22	32			
■ 0: 000000 ■ 10: 001010												
1 : 000001 2 0: 010100												
2 : 000010 2 1: 010101												
4 : 000100 2 2: 010110												
7 : 000111 3 0: 100000												
upper: 1110 <mark>11</mark> 01000111000100												
lower: 00 01 10 00 11 10 00 01 10 00												





Lemma: Elias-Fano Coding

Given an array containing n distinct integers from a universe $\mathcal{U} = [0, u)$, the array can be represented using

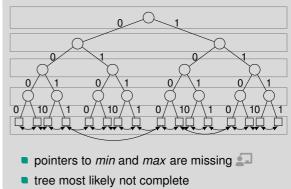
$$n(2 + \log \lceil \frac{u}{n} \rceil)$$
 bits

while allowing O(1) access time and $O(\log \frac{u}{n})$ predecessor/successor time

x-Fast Tries



- each number has w bits
- build binary tree where leaves represent numbers
- edges are labeled 0 or 1
- labels on path from root to leaf are value represented in leaf
- store nodes in hash tables with bit prefix as key
- also store pointer to min and max in right and left subtree
- leaves are stored in doubly linked list
- using perfect hashing on each level requires O(wn) space



x-Fast Tries: Queries



- traversing tree requires O(w) time
- using binary search on levels requires O(log w) time
- if value not found go to *min* or *max* depending on query
- if value is found use doubly linked list to find predecessor or successor
- example on the board

y-Fast Tries



- x-fast trie requires O(wn) space
- group w consecutive objects into one block B_i
- for each block B_i choose maximum m_i as representative
- build x-fast trie for representatives
- store blocks in balanced binary trees
- \blacksquare x-fast trie requires O(n) space
- search in x-fast trie requires $O(\log w) = O(\log \log n)$ time For large n
- search in balanced binary tree requires $O(\log w) = O(\log \log n)$ time

example on the board 🔄

Dynamic y-Fast Trie

- use cuckoo hashing
- representative does not have to be maximum
- any element separating groups suffices
- merge and split blocks that are too small/too big
- query time only expected

Range Minimum Queries



Setting

- array of n integers
- not necessarily sorted

Definition: Range Minimum Queries

Given an array of A of n integers

$$rmq(A, s, e) = \underset{s \le i \le e}{arg \min} A[i]$$

returns the position of minimum in A[s, e]

_	1	_	_	-	_	_	-	_	9
8	2	5	1	9	11	10	20	22	4

- rmq(0,9) = 3
- rmq(0,2) = 1
- rmq(4,8) = 4
- naive in O(1) time
- how much space does a naive O(1)-time solution need PINGO
- using $O(n^2)$ space rmq(s, e) = M[s][e]

Range Minimum Queries in O(1) Time and $O(n \log n)$ Space



- instead of storing all solutions
- store solutions for intervals of length 2^k for every k
- $M[0..n)[0..\lfloor \log n \rfloor)$

Queries

- query rmq(A, s, e) is answered using two subqueries
- let $\ell = |log(e-s-1)|$
- $m_1 = rmq(A, s, s + 2^{\ell} 1)$ and $m_2 = rmq(A, e 2^{\ell} + 1, e)$
- $rmq(A, s, e) = arg min_{m \in \{m_1, m_2\}} A[m]$

Construction

$$M[x][\ell] = rmq(A, x, x + 2^{\ell} - 1)$$

$$= \arg\min\{A[i]: i \in [x, x + 2^{\ell})\}$$

$$= \arg\min\{A[i]: i \in \{rmq(A, x, x + 2^{\ell-1} - 1),$$

$$= rmq(A, x + 2^{\ell-1}, x + 2^{\ell} - 1)\}\}$$

$$= \arg\min\{A[i]: i \in \{M[x][\ell - 1],$$

$$= M[x + 2^{\ell-1}][\ell - 1]\}\}$$

- how much time do we need to fill the table?
 PINGO
- dynamic programming in $O(n \log n)$ time

Range Minimum Queries in O(1) Time and O(n) Space (1/2)



- divide *A* into blocks of size $s = \frac{\log n}{4}$
- blocks B_1, \ldots, B_m with $m = \lceil n/s \rceil$
- query rmq(A, s, e) is answered using at most three subqueries
- one query spanning multiple block
- at most two queries within a block each
- example on the board <a>П

Query Spanning Blocks

- use array B containing minimum within each block
- B has m entries
- use $O(n \log n)$ data structure for B
- $O(m \log m) = O(\frac{n}{s} \log \frac{n}{s}) = O(\frac{n}{\log n} \log \frac{n}{\log n}) = O(n)$
- use additional array B' storing position of minimum in each block
- for queries within block use Cartesian trees

Cartesian Trees (1/2)



Definition: Cartesian Tree

Given an array A of length n, a Cartesian tree C(A)of a is a labeled binary tree with

- root r is labeled with $x = \arg\min\{A[i]: i \in [0, n)\}$
- left and right children of r are Cartesian trees C(A[0,x)) and C(A[x+1,n)) • if interval exists

Lemma: Cartesian Tree Construction

A Cartesian tree for an array of size *n* can be computed in O(n) time

- scan array from left to right
- insert each element by
 - following rightmost path from leaf to root till element can be inserted
 - everything below becomes left child of new node
- each node is removed at most once from the rightmost path
- moving subtree to left child in constant time gives O(n) construction time
- example on the board





Lemma: Equality of Cartesian Trees

Given two arrays A and B of length n with equal Cartesian trees, then

$$rmq(A, s, e) = rmq(B, s, e)$$

for all 0 < s < e < n

- proof by induction over the size of the array
- if the array has size one, this is true
- assuming this is correct for arrays of size n, showing this for arrays of size n + 1 uses recursive definition of Cartesian trees



Range Minimum Queries in O(1) Time and O(n) Space (2/2)

Query Within a Block

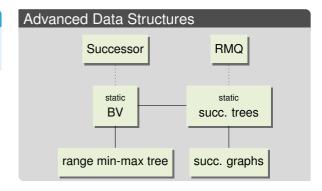
- consider every possible Cartesian tree for arrays of size $s = \frac{\log n}{4}$
- tree can be represented using 2s + 1 bits
- store bit representation of Cartesian tree for every block
- for every possible Cartesian tree and every start and end position store position of minimum
- $O(2^{2s+1} \cdot s \cdot s \cdot \log s) =$ $O(\sqrt{n}\log^2 n \cdot \log \log n) = O(n)$ space





This Lecture

- successor and predecessor data structures
- range minimum query data structures



Bibliography I



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